

# **Information-Entropy Measure for Evaluation of Image Quality**

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## **Abstract:**

This paper presents a simple and straightforward method for synthetically evaluating digital radiographic images by a single parameter in terms of transmitted information (TI). The features of our proposed method are: (1) simplicity of computation, (2) simplicity of experimentation, and (3) combined assessment of image noise and resolution (blur). Two acrylic step wedges with 0-1-2-3-4-5 mm and 0-2-4-6-8-10 mm in thickness were used as phantoms for experiments. In the present study, three experiments were conducted. First, in order to investigate the relation between the value of TI and image noise, various radiation doses by changing exposure time were employed. Second, we examined the relation between the value of TI and image blurring by shifting the phantoms away from the center of the x-ray beam area toward the cathode end when imaging was performed. Third, we analyzed the combined effect of deteriorated blur and noise on the images by employing three smoothing filters. Experimental results show that the amount of TI is closely related to both image noise and image blurring. The results demonstrate the usefulness of our method for evaluation of physical image quality in medical imaging.

**Key words:** medical images, image quality, image processing, information entropy, performance evaluation

## INTRODUCTION

In medical imaging, image quality is determined by at least five factors: contrast, resolution, noise, artifacts, and distortion. Of these factors, resolution and noise are the most commonly used physical characteristics. As is well known, they are described by the modulation transfer function (MTF) and noise power spectrum (NPS), respectively. The MTF describes the ability of an imaging system to reproduce the frequency information contained in the incident x-ray signal. The NPS describes the frequency content of the noise of an imaging system. However, one of the dilemmas in medical radiography is the extent to which these metrics affect image quality. In comparison of two imaging systems, for example, an imaging system may only be superior in one metric while being inferior to another in the other metric. To deal with this issue, the noise equivalent quanta or detective quantum efficiency, which can be calculated if the MTF, NPS, and the input signal-to-noise ratio of the x-ray beam used to measure the NPS are known, is used as a single parameter to describe the general quality of the system.<sup>1,2</sup>

In this study, we present a simple and straightforward method for synthetically evaluating digital radiographic images by a single parameter in terms of Shannon's entropy (information entropy).<sup>3,4</sup> Our proposed method is considered as an alternative

to the currently available metrics for evaluation of image quality. The concept of information entropy describes with how much randomness (or uncertainty) there is in a signal or an image, in other words, how much information is provided by the signal or image. If the uncertainty is measured before and after imaging, the reduction in the uncertainty, *i.e.*, information entropy is a quantitative measure of the information transmitted by the image. The image quality then can be quantitatively compared when the transmitted information provided by the images are known. From the physical measurement's point of view, the more the information transmitted, the better the image quality is.

To the best of our knowledge, the research that initially led to the introduction of transmitted information as an image-quality measure dates back to the late 1970s. Uchida and Tsai first introduced a method in terms of entropy for quality evaluation of radiographic images and applied this method to assess the quality of tank-developed images and that of automatic processor-developed images.<sup>5</sup> They demonstrated that the quality of radiographic images were largely affected by the characteristics of X-ray apparatus, exposure factors, intensifying screen-film system, and film development process. If all of these parameters affecting the image quality are kept unvaried except the film development method, the performance of development methods can be quantitatively assessed by comparing the amounts of information contributed by tank-developed images and automatic processor-developed images. After this

publication, limited work using the transmitted information (TI) as an image-quality measure for image assessment has been reported.<sup>6,7</sup> though a great deal of work on mutual-information-based registration of mono-modality and multimodality medical images has been devoted since the early 1990s.<sup>8-17</sup>

The present paper is a significant extension of our previous work,<sup>5</sup> applying the methodology to the field of digital medical imaging. The features of our proposed method are: (1) simplicity of computation, (2) simplicity of experimentation, and (3) combined assessment of noise and resolution (blur) by a single number. In this study, in order to validate the usefulness of our proposed method, three experiments were given.

## **THEORETICAL FRAMEWORK**

Transmitted information (TI) is a concept from information theory. We briefly describe the TI as follows.

Given events  $S_1, \dots, S_n$  occurring with probabilities  $p(S_1), \dots, p(S_n)$ , then the average uncertainty associated with each event is defined by the Shannon entropy as

$$H(S) = -\sum_{i=1}^n p(S_i) \cdot \log_2 p(S_i), \quad (1)$$

Considering  $x$  and  $y$  as two random variables corresponding to an input variable and an output variable, the entropy for the input and that for the output are denoted as

$H(x)$  and  $H(y)$ , respectively. For this case the joint entropy,  $H(x,y)$ , is defined as

$$H(x, y) = H(x) + H_x(y) = H(y) + H_y(x) \quad , \quad (2)$$

where  $H_x(y)$  and  $H_y(x)$  are conditional entropies. They are the entropy of the output when the input is known, and that of the input when the output is known, respectively.

In this situation we can compute TI,  $T(x;y)$ , as:

$$\begin{aligned} T(x; y) &= H(x) - H_y(x) = H(y) - H_x(y) \\ &= H(x) + H(y) - H(x, y) \quad . \end{aligned} \quad (3)$$

A useful way of visualizing the relationship between these entropies is provided by a Venn diagram as shown in Figure 1. Consider an experiment in which every input has a unique output belonging to one of various output categories. In this study, for simplicity, the inputs may be considered to be a set of subjects (e.g., phantoms in simplicity) varying in composition, while the outputs may be their corresponding images varying in optical density or gray level. An orderly system firstly established by Attneave is employed in the present study to calculate the entropies of input, output, and their joint entropies.<sup>18</sup> With this orderly system, the amount of TI is easily computed. The frequency, with which each output is made to each input, is recorded in Table 1. The columns and rows of this table represent various inputs and outputs. The various inputs,  $x_1, x_2, \dots, x_i, \dots, X$ , are assumed to take discrete values of input variables  $x$ . Likewise, the various outputs,  $y_1, y_2, \dots, y_j, \dots, Y$  are discrete values of output variables  $y$ . The upper-case  $X$  and  $Y$  stand for the number of input and output categories, respectively. Note that the subscript  $i$  refers to any particular but

unspecified input while the subscript  $j$  refers to any particular but unspecified output.

The number of times input  $x_i$  presented will be symbolized by  $n_i$ , the frequency of output,  $y_j$ , by  $n_j$ , and the frequency, with which the input  $x_i$  corresponds to the output  $y_j$ , is given by  $n_{ij}$ . The total of all frequencies is given by  $n$ . It is apparent from Table 1 that

$$\sum_j n_{ij} = n_i \quad (4)$$

$$\sum_i n_{ij} = n_j \quad (5)$$

$$\sum_{ij} n_{ij} = \sum_i n_i = \sum_j n_j = n \quad . \quad (6)$$

Referring to the definition of information entropy as shown in Equation (1), three informational quantities, namely,  $H(x)$ ,  $H(y)$ , and  $H(x,y)$  can be calculated from

Table 1.

$$H(x) = \sum_i p_i \log_2 \frac{1}{p_i} \quad (7)$$

$$H(y) = \sum_j p_j \log_2 \frac{1}{p_j} \quad (8)$$

$$H(x,y) = \sum_{ij} p_{ij} \log_2 \frac{1}{p_{ij}} \quad , \quad (9)$$

where  $p_i=n_i/n$ ,  $p_j=n_j/n$ , and  $p_{ij}=n_{ij}/n$ . For simplicity, we can rewrite the above equations as follows.

$$H(x) = \log_2 n - \frac{1}{n} \sum_i n_i \log_2 n_i \quad (10)$$

$$H(y) = \log_2 n - \frac{1}{n} \sum_j n_j \log_2 n_j \quad (11)$$

$$H(x,y) = \log_2 n - \frac{1}{n} \sum_{ij} n_{ij} \log_2 n_{ij} \quad , \quad (12)$$

Then the transmitted information  $T(x;y)$  can be obtained from Equation (3) together

with Equations (10), (11), and (12). The transmitted information conveys the amount of information that “y” has about “x”.

Table 2 gives an example of how to calculate the transmitted information. Assume that a subject (eg, a step-wedge) having five steps with different thickness was used for the experiment. The five steps correspond to five inputs present equiprobably. The gray-scale pixel values of 100 pixels in each step after imaging were measured randomly. The distributions of the pixel values are considered as the corresponding outputs and their respective frequencies are given in the table. The frequencies will be referred to by means of the symbols given in the preceding table; for example:  $n_{12}=60$ ,  $n_{j=3}=118$ ,  $n_{i=2}=100$ ,  $n=500$ , and so on. Now, there are three information quantities, namely,  $H(x)$ ,  $H(y)$ , and  $H(x,y)$ , can be calculated directly from the table by using equations (10), (11), and (12).

For the data given in Table 2,

$$H(x) = \log_2 n - \frac{1}{n} \sum_i n_i \log_2 n = \log_2 5 = 2.323 \quad (\text{since inputs are equiprobable})$$

$$H(y) = \log_2 500 - \frac{1}{500} (20 \log_2 20 + 64 \log_2 64 + 118 \log_2 118 \dots \text{etc.}) = 2.575$$

$$H(x, y) = \log_2 500 - \frac{1}{500} (20 \log_2 20 + 60 \log_2 60 + 4 \log_2 4 \dots \text{etc.}) = 3.235$$

Applying Equation (3) to the values calculated above, we have

$$T(x; y) = H(x) + H(y) - H(x, y) = 2.323 + 2.575 - 3.235 = 1.663.$$

This is the estimate of the amount of information transmitted by the subject from input to output: 1.633 bits, out of a possible of 2.323 bits.



## METHODS AND MATERIALS

In the present study, three experiments were made. The first experiment was conducted to verify the effect of noise, the second for analyzing the effect of resolution (blur) and finally for the third experiment three filters were used to analyze the combined effect of deteriorated blur and noise on the images.

Two acrylic step wedges with 0-1-2-3-4-5 mm (step wedge A) and 0-2-4-6-8-10 mm (step wedge B) in thickness were prepared as phantoms for experiments. The specified exposure factors were kept at 42kV and 10mA, and the focus-imaging distance was taken as 185cm but the exposure time was varied ranging from 0.1 sec to 0.5 sec. An imaging plate for computed radiography was used as a detector to record x-ray intensities. It is clear that when the thickness of the step wedge increases, the intensity of the transmitted x-ray beam is reduced. Therefore, the image consists of a graduated scale of gray levels with different values. Figure 2 shows a schematic drawing of an acrylic step wedge and an image obtained from a step wedge used in the present study. A region of interest (ROI) located at the center of each step of the step wedge was selected for computation of pixel-value distribution. The area of the ROI used in the present study was 100×100 pixels. Therefore a total of 10 000 data for each step was obtained. Ten images for a particular exposure time were obtained for the present study.

Furthermore, in order to investigate the relationship between the extent of image blurring and the amount of TI, we changed the effective focal spot sizes of x-ray tube by shifting the phantoms away from the center of the x-ray beam area toward the cathode end when imaging was performed. Since the effective focal spot size changes and becomes larger for points toward the cathode end of the field.<sup>19</sup> The increase of effective focal spot size results in the degradation of resolution (blur). In order to accurately measure the extent of blurring attributed to the change the effective focal spot size, ROIs having the area of 200×50 pixels located at the boundary of two adjacent steps were selected.

Three commonly used smoothing filters, averaging, median and Gaussian filters<sup>20</sup> were employed to analyze the combined effect of blur and noise on the processed images. The images of the step wedges A and B were used as original images. After applying the three filters individually to the step-wedge images, the transmitted information as well as other values related to noise and blur on the processed images were calculated and compared.

## **RESULTS AND DISCUSSION**

Figure 3 shows the relation between the relative exposure dose and TI,  $T(x;y)$ , for

the images of two step wedges. The results illustrate that the  $T(x;y)$  increases with the increase of exposure dose. The rise of  $T(x;y)$  is considered due to the decrease of noise resulting from the increase of radiation dose. As shown in Figure 4, the value of the conditional entropy  $H_x(y)$  decreases when exposure dose increases. A previous study reported by Uchida and Fujita indicated that the  $H_x(y)$  is closely related to the noise of an imaging system.<sup>7</sup> The lower the noise level (the higher the exposure dose), the less the  $H_x(y)$  value is. Our results well agree with the results of this literature. Figure 5 shows the root-mean-square (RMS) noise. Figure 5(a) and (b) presents the RMS value for each step of step wedges A and B as a function of exposure dose, respectively. The average RMS values of the two step wedges are provided in Figure 5(c). It is apparent from the figures that the RMS value decreases with the increase of exposure dose. This result reveals the reasoning that  $H_x(y)$  is associated with noise present in an information transmission channel. Thus, it is obvious from the experiments obtained that TI value and the extent of noise are closely correlated.

Figure 6 shows the  $T(x;y)$  values obtained by shifting the step wedges 15cm and 30cm away from the center of the x-ray beam area toward the cathode end. The calculated results show that the TI becomes lower when the off-center distance is greater. This means that the TI value decreases when blur is deteriorated. We also compared the RMS noise computed from the step-wedge image without and with shifting from the center. The results showed no significant difference between the two

cases (without and with shifting). Similarly, as shown in Figure 7,  $H_x(y)$  values obtained from the two cases for the two step wedges show insignificant difference. The calculated values of TI and  $H_x(y)$  obtained at the relative exposure doses 20 and 30 for three different exposure positions are summarized in Table 3. The results imply that the decrease of the TI may be mainly due to image blurring resulting from the increase of the effective focal spot size. Therefore, the TI is also closely correlated with resolution (blur) of imaging systems.

Figure 8 shows the TI as a function of the relative exposure for the step-wedge images processed by the three filters having filter size of  $5 \times 5$ . The calculated results of the original image are also illustrated for comparison. The experimental results indicate that averaging filter provides the best performance, followed by median and Gaussian filters. Similar performance rankings were obtained when the filter sizes were  $3 \times 3$  and  $7 \times 7$ . In order to visually differentiate among the three processed images together with the original image, we iteratively performed image processing 3 times. Figure 9 shows an example of the processed image data. It can be observed from the figure that image noise level on the three processed images has been reduced, whereas the images were deteriorated and blurred in different extent. Table 4 gives the quantitative comparison among the processed images. It is noted from the table that the averaging filter provides the highest TI, followed by the median and Gaussian filters. In contrast, the averaging filter provides the lowest conditional entropy  $H_x(y)$  and RMS

noise followed by the median and Gaussian. Furthermore, we measured the extent of image blurring using an index “edge slope”. In this study the edge slope is defined as the gradient of the mean pixel-value profile across the edges of two adjacent steps. The mean profile was obtained by averaging 100 individual ones. As illustrated in the table, the edge slope of the original image is higher as compared with that of the three processed images. The edge slopes of median and Gaussian filters are almost the same and higher than that of averaging filter. As a whole, the performance rankings of the three smoothing filters are in the order of averaging, median and Gaussian. Furthermore, from Figure 9 and Table 4, we note that the perceptual and quantitative results are in good agreement. The results show that the combined effect of deteriorated blur and noise on the images can be analyzed and evaluated using the TI metric.

Our proposed method has limitations. First, an appropriate selection of test object (eg, step wedges in the present study) is required. In other words, the adjacent pixel-value distributions obtained from the input must be partially overlapped (see Table 2). When the pixel-value distributions are completely separated, the TI value will exactly equal input entropy  $H(x)$ . If this case occurs, the proposed metric then can not be used for evaluation of imaging properties. Second, the TI value does not provide frequency information like MTF and NPS do. Also, other noise contributing properties such as the electronic noise and structural noise cannot be separately represented. A

comparison of our proposed metric with MTF and NPS in the same context is need and is in progress in our ongoing study. Furthermore, this paper did not attempt to conduct the analysis of quantitative influence of image noise and image blurring on the amount of TI. Thus, the extent to which these two factors individually affect the amount of the TI still remains unclear. We will investigate this issue in our future research.

## **CONCLUSIONS**

In this work, we presented a metric using transmitted information for measurement of physical image quality. Our experimental results showed that the amount of transmitted information is correlated with both image noise and image blurring. The results indicate the potential usefulness of the proposed method for evaluation of physical image quality.

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## **Figure Captions**

Fig 1. Venn diagram which represents the relationship between input entropy  $H(x)$  and output entropy  $H(y)$ , conditional entropies  $H_x(y)$  and  $H_y(x)$ , joint entropy  $H(x,y)$  and the transmitted information  $T(x;y)$ . The amount of each entropy and transmitted information are shown by each area in the diagram.

Fig 2. (a) Schematic drawing of an acrylic step wedge. (b) An image obtained from a step wedge used in the study.

Fig 3. Transmitted information  $T(x;y)$  as a function of relative exposure dose for the images obtained from two step wedges. For example, the values of  $T(x;y)$  at the relative exposure doses of 20 and 30 for step wedge A are  $2.26 \pm 0.01$  [bit] and  $2.44 \pm 0.01$  [bit], and that for step wedge B are  $1.12 \pm 0.03$  [bit] and  $1.35 \pm 0.04$  [bit], respectively. Values shown are expressed as mean  $\pm$  standard deviation.

Fig 4. Conditional entropy  $H_x(y)$  as a function of relative exposure dose for the images obtained from two step wedges. For example, the values of  $H_x(y)$  at the relative exposure doses of 20 and 30 for step wedge A are  $6.55 \pm 0.01$  [bit] and  $6.29 \pm 0.01$  [bit], and that for step wedge B are  $6.34 \pm 0.02$  [bit] and  $6.10 \pm 0.01$  [bit], respectively. Values shown are expressed as mean  $\pm$  standard deviation.

Fig 5. Root mean square (RMS) noise as a function of relative exposure dose for the images obtained from two step wedges. (a) RMS for each step (step 0 ~step5) of step wedge A, (b) RMS for each step (step 0 ~step5) of step wedge B, and (c) Average RMS obtained by averaging the RMS of various steps. For example, the values of RMS at relative exposure doses of 20 and 30 for step wedge A are  $23.17 \pm 0.09$  and  $19.34 \pm 0.13$ , and that for step wedge B are  $20.46 \pm 0.24$  and  $16.79 \pm 0.17$ , respectively. Values shown are expressed as mean  $\pm$  standard deviation.

Fig 6. Transmitted information  $T(x;y)$  as a function of the relative exposure dose for three different exposure positions to the step wedges: center position of the x-ray beam area, 15cm and 30 cm apart from the center toward the cathode end. (a) Step wedge A. (b) Step wedge B. Several typical values of the transmitted information are summarized in Table 3.

Fig 7. Conditional entropy  $H_x(y)$  as a function of the relative exposure dose for three different exposure positions to the step wedges: center position of the x-ray beam area, 15cm and 30 cm apart from the center toward the cathode end. (a) Step wedge A. (b) Step wedge B. Several typical values of the transmitted information are given in Table 3.

Fig 8. Transmitted information  $T(x;y)$  as a function of the relative exposure for the step-wedge images processed by the three filters having filter size of  $5 \times 5$ . The calculated result of the original image is also shown for comparison. (a) Step wedge A. (b) Step wedge B.

Fig 9. An example of the processed image data. (a) Image of the step wedge used. (b) Magnification of the rectangular area shown in (a). (c) Magnified image processed by averaging filter. (d) Magnified image processed by median filter. (e) Magnified image processed by Gaussian filter. In order to visually differentiate among the three processed images together with the original image, we iteratively performed image processing 3 times. The calculated results of  $T(x;y)$ ,  $H_x(y)$ , RMS, and edge slope are summarized in Table 4.

**Table 1.** A data matrix of frequency for  $Y$  outputs to  $X$  inputs. The columns and rows of this table represent various discrete inputs and outputs. The capitals  $X$  and  $Y$  stand for the number of input and output categories, respectively. The total of all frequencies is given by  $n$ .

		Input $x$							
		$x_1$	$x_2$	--	$x_i$	--	--		$X$
Output $y$	$y_1$	$n_{11}$	$n_{21}$	--	$n_{i1}$	--	--	$n_{X1}$	$n_{j=1}$
	$y_2$	$n_{12}$	$n_{22}$	--	$n_{i2}$	--	--	$n_{X2}$	$n_{j=2}$
	$y_3$	$n_{13}$	$n_{23}$	--	$n_{i3}$	--	--	$n_{X3}$	$n_{j=3}$
		--	--	--	--	--	--	--	--
	$y_j$	$n_{1j}$	$n_{2j}$	--	$n_{ij}$	--	--	$n_{Xj}$	$n_{j=j}$
		--	--	--	--	--	--	--	--
	$Y$	$n_{1Y}$	$n_{2Y}$	--	$n_{iY}$	--	--	$n_{XY}$	$n_{j=Y}$
		$n_{i=1}$	$n_{i=2}$	--	$n_{i=i}$	--	--	$n_{i=X}$	<b><math>n</math></b>

**Table 2. An example of how to calculate the transmitted information. The frequencies shown in the table is referred to by means of the symbols given Table 1: for example,  $n_{23}=88$ ,  $n_{j=2}=64$ ,  $n_{i=1}=100$ ,  $n=500$ , and so on.**

		Input $x$					
		1	2	3	4	5	
Output $y$	1	20					20
	2	60	4				64
	3	20	88	10			118
	4		8	76	14		98
	5			12	80	2	94
	6			2	6	8	16
	7					90	90
		100	100	100	100	100	500

Table 3. Several typical values of transmitted information  $T(x;y)$  and conditional entropy  $H_x(y)$  obtained at the relative exposure doses of 20 and 30 for three different exposure positions. Values shown are expressed as mean $\pm$  standard deviation.

Stepwedge	Relative exposure dose	Position	$T(x;y)$ [bit]	$H_x(y)$ [bit]
A	20	center	1.72 $\pm$ 0.03	6.56 $\pm$ 0.04
		off center 15cm	1.61 $\pm$ 0.01	6.51 $\pm$ 0.01
		off center 30cm	1.57 $\pm$ 0.01	6.65 $\pm$ 0.01
	30	center	1.92 $\pm$ 0.01	6.37 $\pm$ 0.01
		off center 15cm	1.86 $\pm$ 0.01	6.24 $\pm$ 0.02
		off center 30cm	1.83 $\pm$ 0.01	6.25 $\pm$ 0.01
B	20	center	0.76 $\pm$ 0.03	6.32 $\pm$ 0.01
		off center 15cm	0.60 $\pm$ 0.03	6.26 $\pm$ 0.01
		off center 30cm	0.52 $\pm$ 0.01	6.24 $\pm$ 0.01
	30	center	0.95 $\pm$ 0.03	6.04 $\pm$ 0.01
		off center 15cm	0.77 $\pm$ 0.02	5.90 $\pm$ 0.01
		off center 30cm	0.71 $\pm$ 0.02	5.96 $\pm$ 0.01

**Table 4. Values of transmitted information  $T(x;y)$ , conditional entropy  $H_x(y)$ , noise level RMS and edge slop for three filter-processed images and original image**

Image	$T(x;y)$ [bit]	$H_x(y)$ [bit]	RMS	Edge slope
Averaging	2.55	5.75	13.2	10.6
Median	2.48	6.03	16.7	14.8
Gaussian	2.26	6.47	21.9	15
Original	1.89	6.97	31.3	17.2

The exposure conditions used to obtain the original images were:

42kV, 10mA, 0.1 sec.

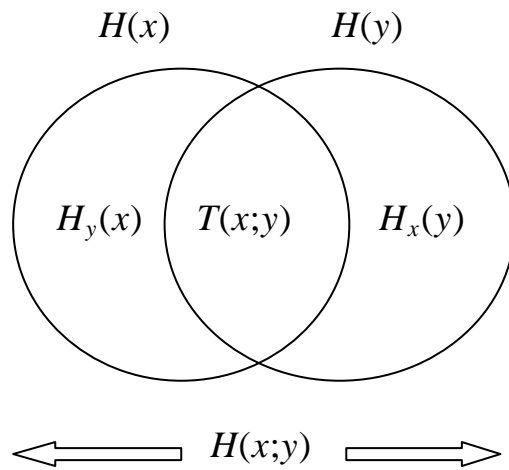


Fig 1. Venn diagram which represents the relationship between input entropy  $H(x)$  and output entropy  $H(y)$ , conditional entropies  $H_x(y)$  and  $H_y(x)$ , joint entropy  $H(x,y)$  and the transmitted information  $T(x;y)$ . The amount of each entropy and transmitted information are shown by each area in the diagram.



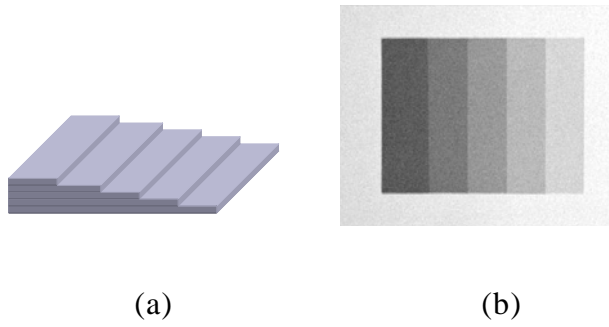


Fig 2. (a) Schematic drawing of an acrylic step wedge. (b) An image obtained from a step wedge used in the study.

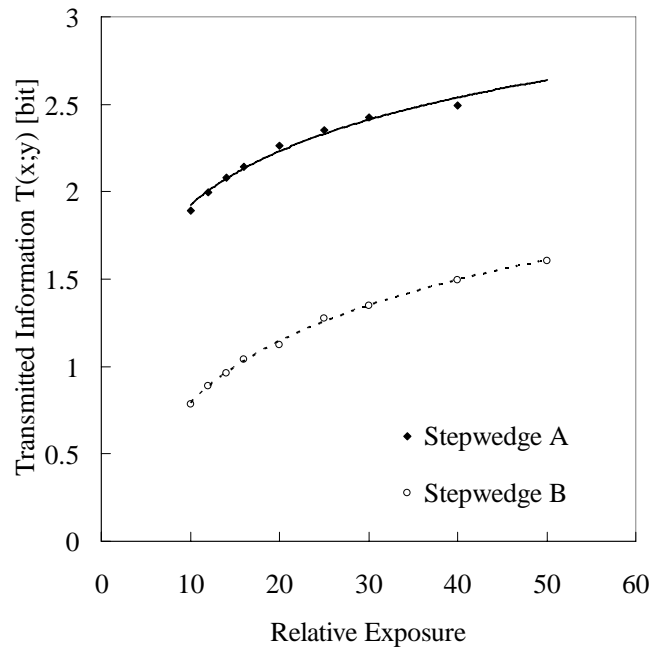


Fig 3. Transmitted information  $T(x;y)$  as a function of relative exposure dose for the images obtained from two step wedges. For example, the values of  $T(x;y)$  at the relative exposure doses of 20 and 30 for step wedge A are  $2.26 \pm 0.01$  [bit] and  $2.44 \pm 0.01$  [bit], and that for step wedge B are  $1.12 \pm 0.03$  [bit] and  $1.35 \pm 0.04$  [bit], respectively. Values shown are expressed as mean  $\pm$  standard deviation.

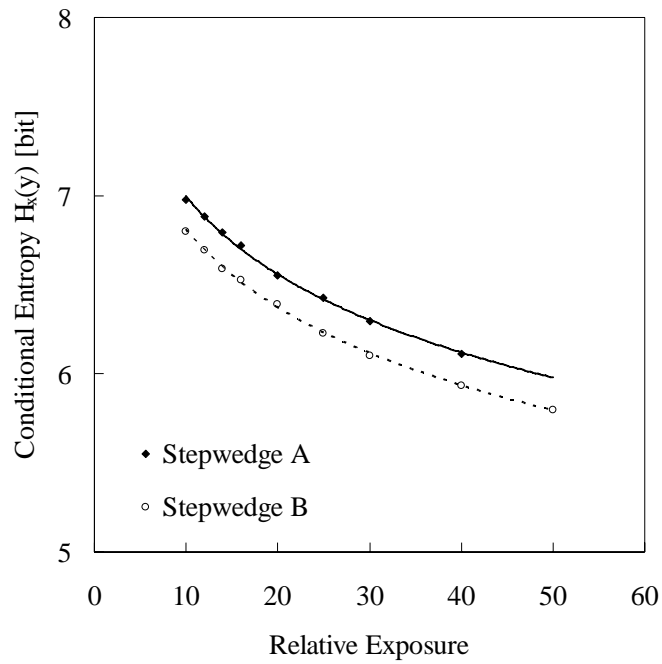


Fig 4. Conditional entropy  $H_x(y)$  as a function of relative exposure dose for the images obtained from two step wedges. For example, the values of  $H_x(y)$  at the relative exposure doses of 20 and 30 for step wedge A are  $6.55 \pm 0.01$  [bit] and  $6.29 \pm 0.01$  [bit], and that for step wedge B are  $6.34 \pm 0.02$  [bit] and  $6.10 \pm 0.01$  [bit], respectively. Values shown are expressed as mean  $\pm$  standard deviation.

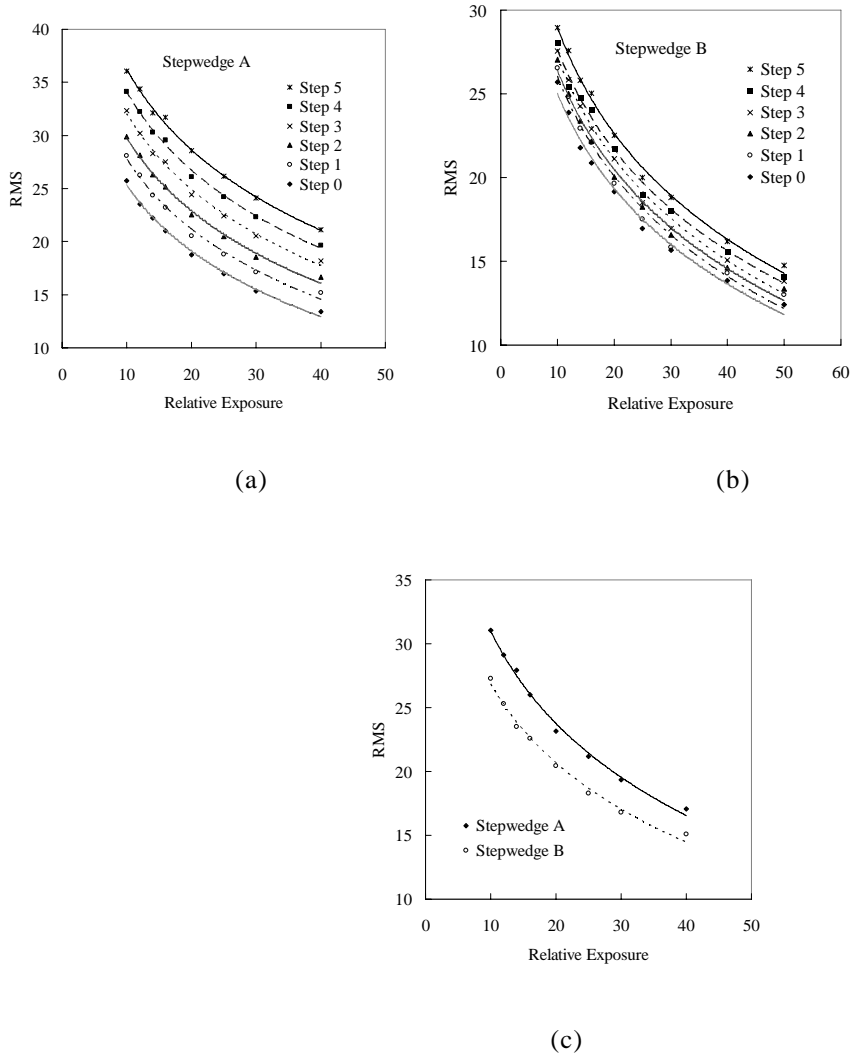
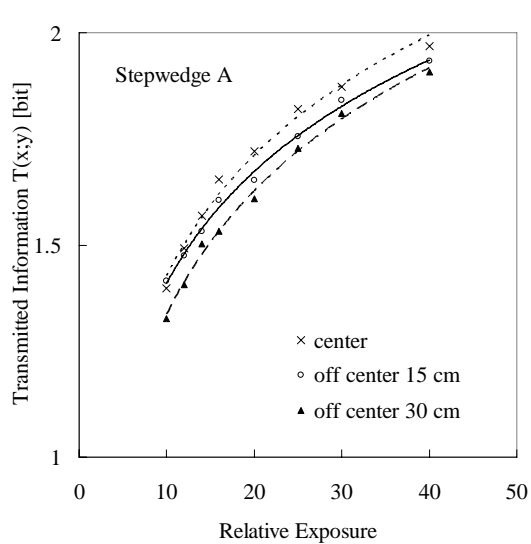
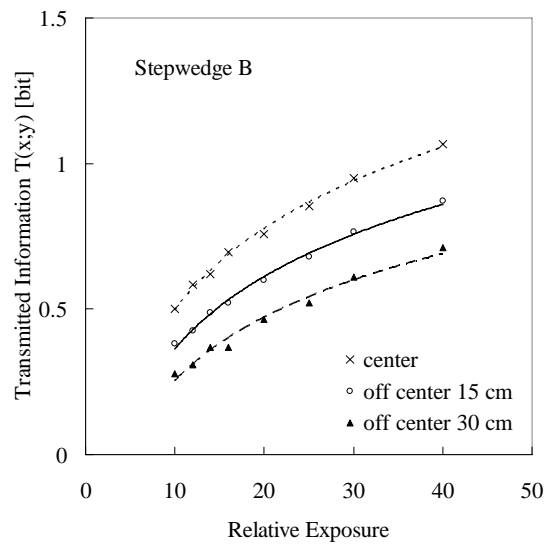


Fig 5. Root mean square (RMS) noise as a function of relative exposure dose for the images obtained from two step wedges. (a) RMS for each step (step 0 ~step5) of step wedge A, (b) RMS for each step (step 0 ~step5) of step wedge B, and (c) Average RMS obtained by averaging the RMS of various steps. For example, the values of RMS at relative exposure doses of 20 and 30 for step wedge A are  $23.17 \pm 0.09$  and  $19.34 \pm 0.13$ , and that for step wedge B are  $20.46 \pm 0.24$  and  $16.79 \pm 0.17$ , respectively. Values shown are expressed as mean  $\pm$  standard deviation.



(a)



(b)

Fig 6. Transmitted information  $T(x;y)$  as a function of the relative exposure dose for three different exposure positions to the step wedges: center position of the x-ray beam area, 15cm and 30 cm apart from the center toward the cathode end. (a) Step wedge A. (b) Step wedge B. Several typical values of the transmitted information are summarized in Table 3.

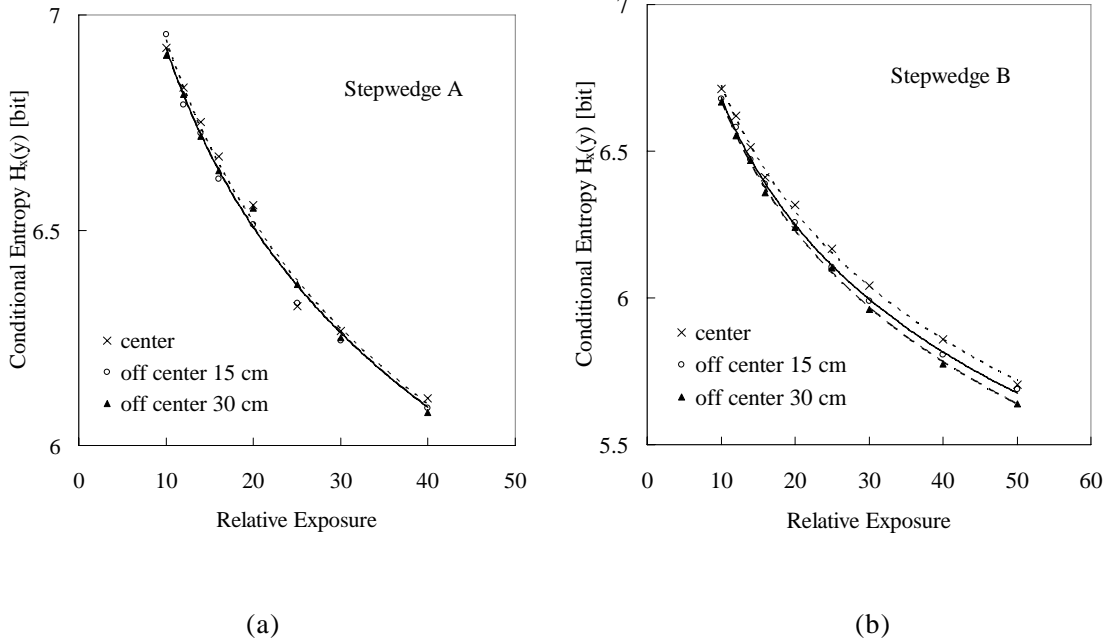
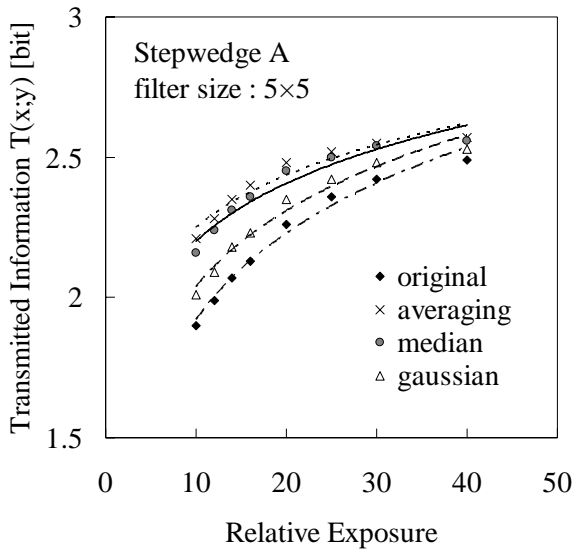
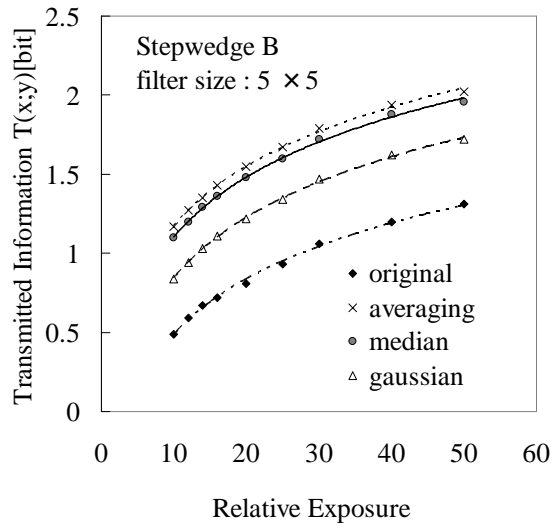


Fig 7. Conditional entropy  $H_x(y)$  as a function of the relative exposure dose for three different exposure positions to the step wedges: center position of the x-ray beam area, 15cm and 30 cm apart from the center toward the cathode end. (a) Step wedge A. (b) Step wedge B. Several typical values of the transmitted information are given in Table 3.



(a)



(b)

Fig 8. Transmitted information  $T(x;y)$  as a function of the relative exposure for the step-wedge images processed by the three filters having filter size of  $5 \times 5$ . The calculated result of the original image is also shown for comparison. (a) Step wedge A. (b) Step wedge B.

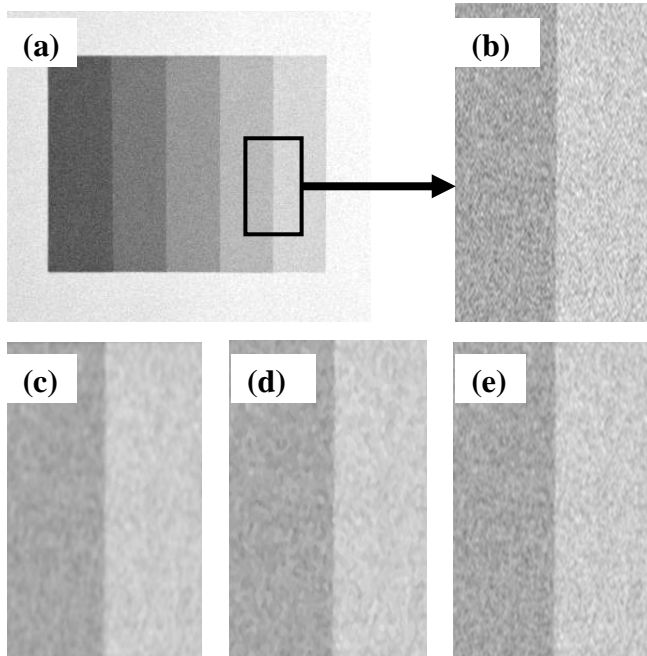


Fig 9. An example of the processed image data. (a) Image of the step wedge used. (b) Magnification of the rectangular area shown in (a). (c) Magnified image processed by averaging filter. (d) Magnified image processed by median filter. (e) Magnified image processed by Gaussian filter. In order to visually differentiate among the three processed images together with the original image, we iteratively performed image processing 3 times. The calculated results of  $T(x;y)$ ,  $H_x(y)$ , RMS, and edge slope are summarized in Table 4.



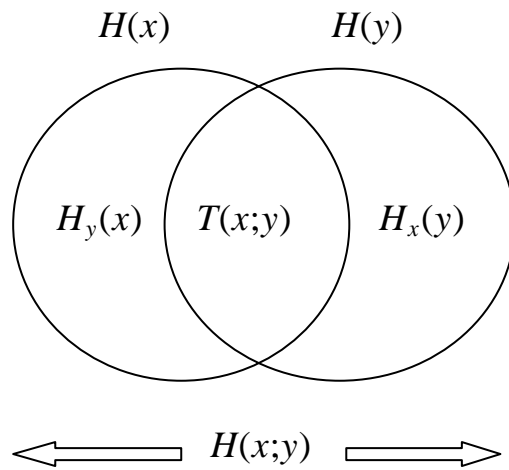


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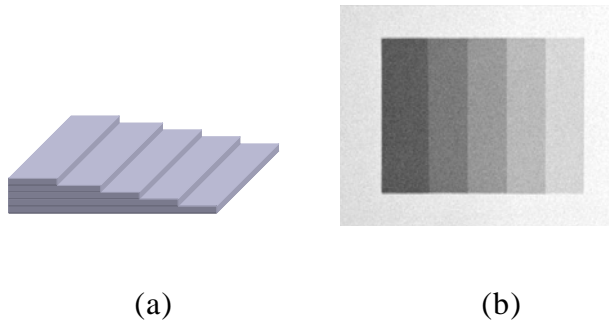


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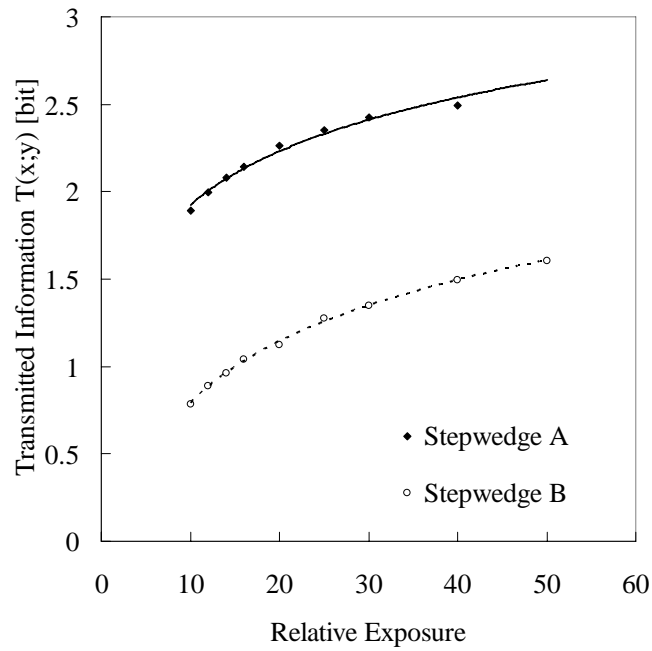


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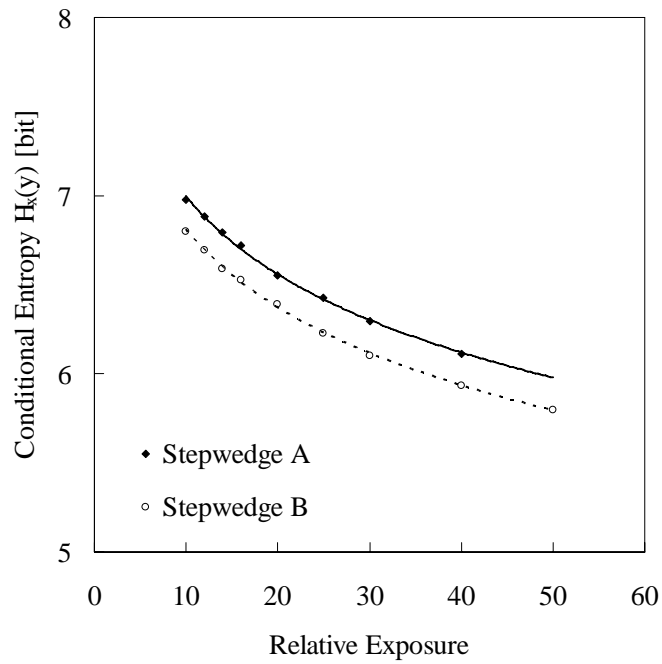


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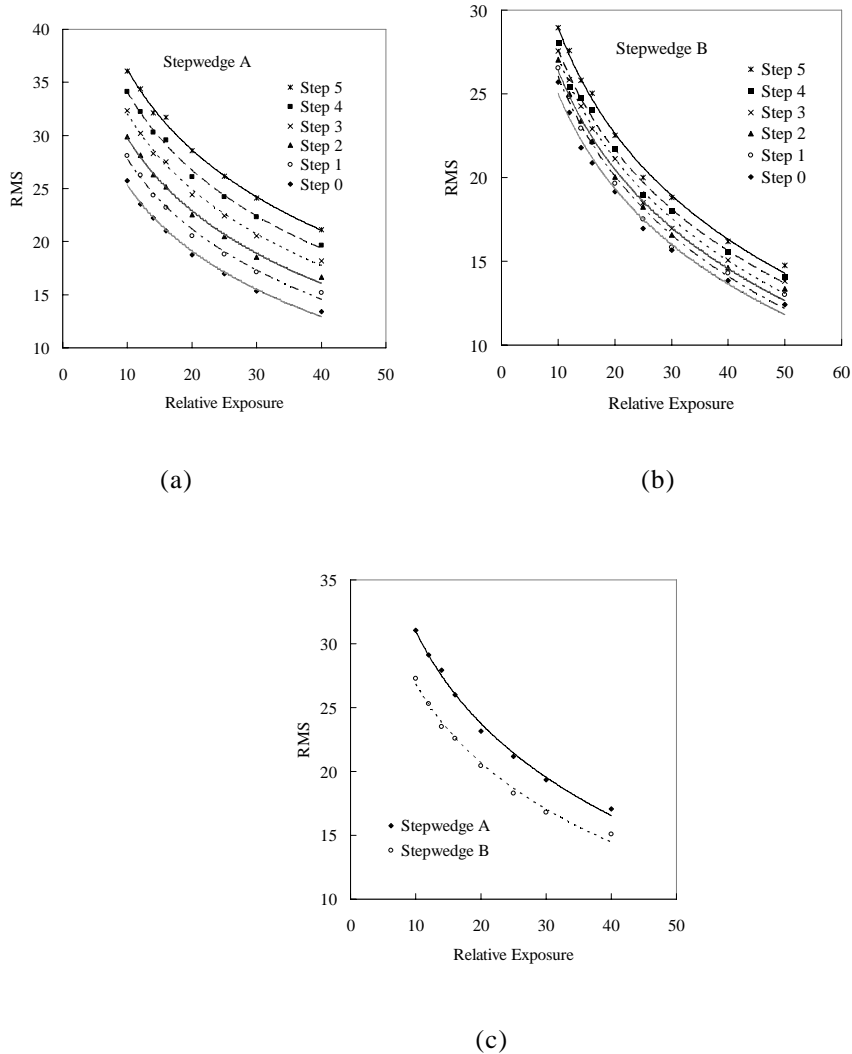
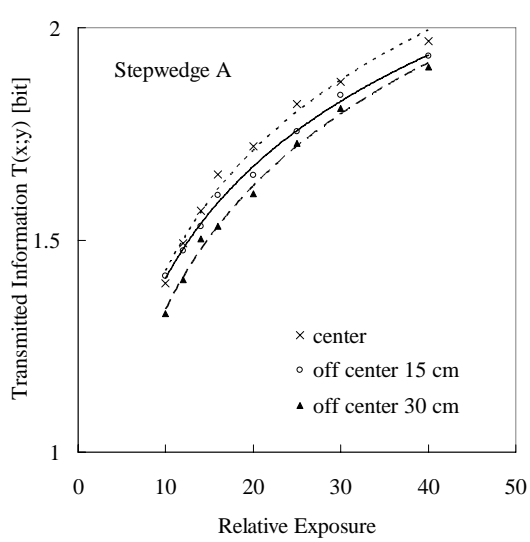
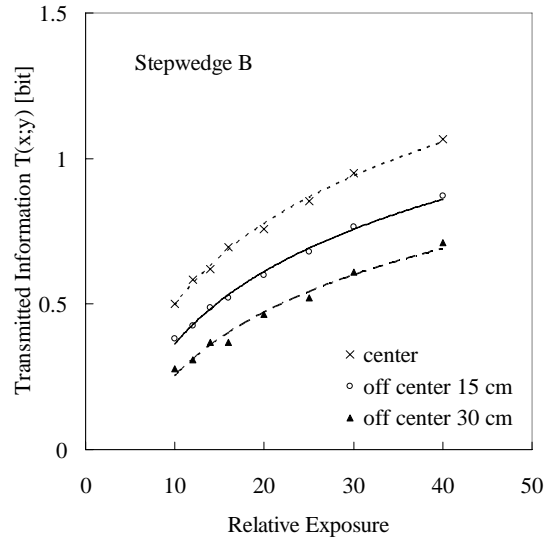


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(a)



(b)

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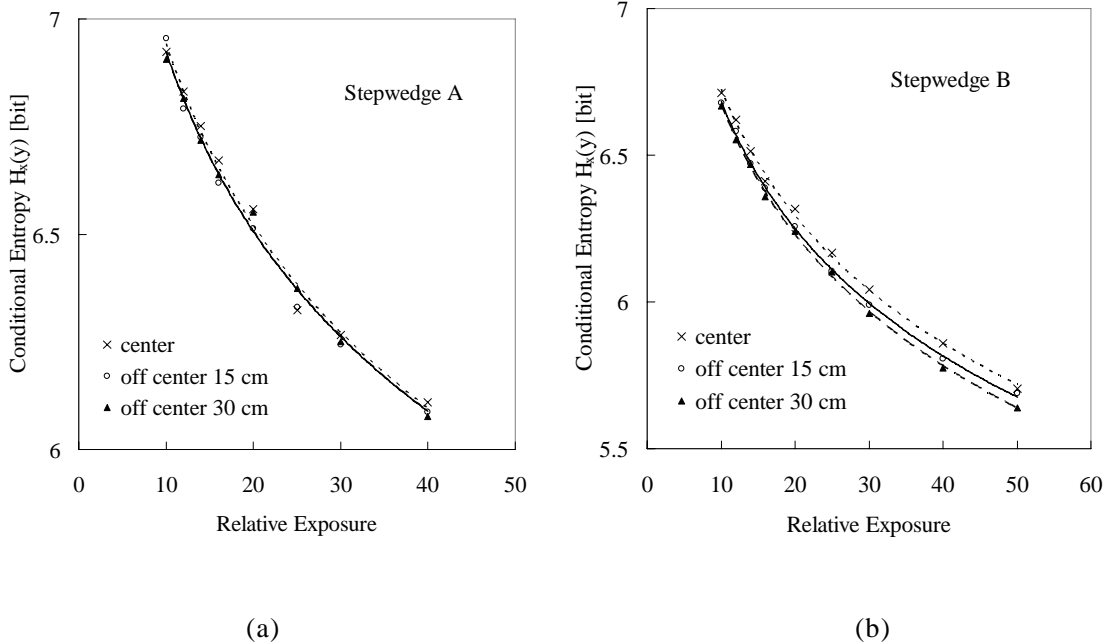
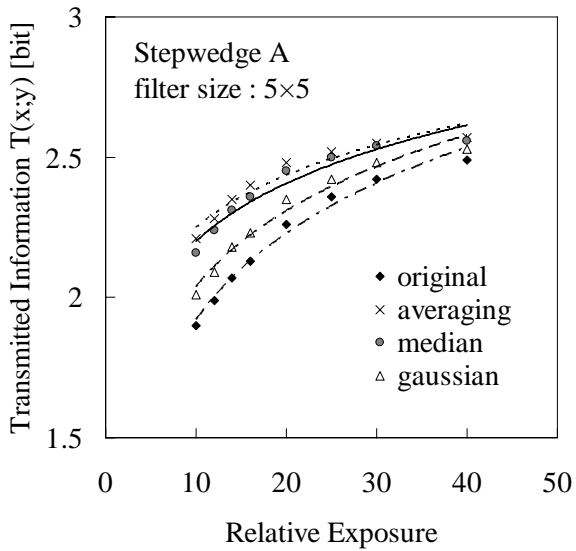
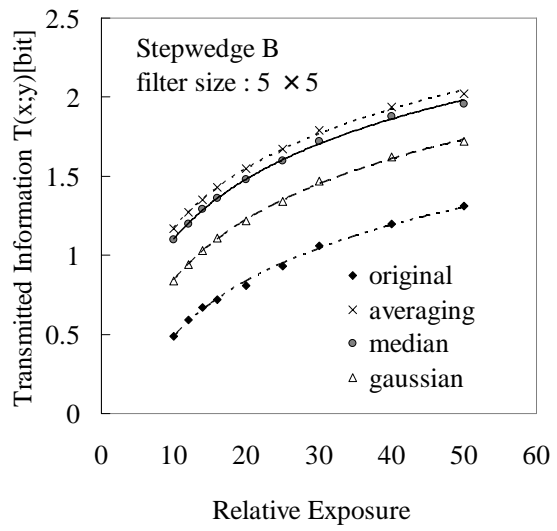


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(a)



(b)

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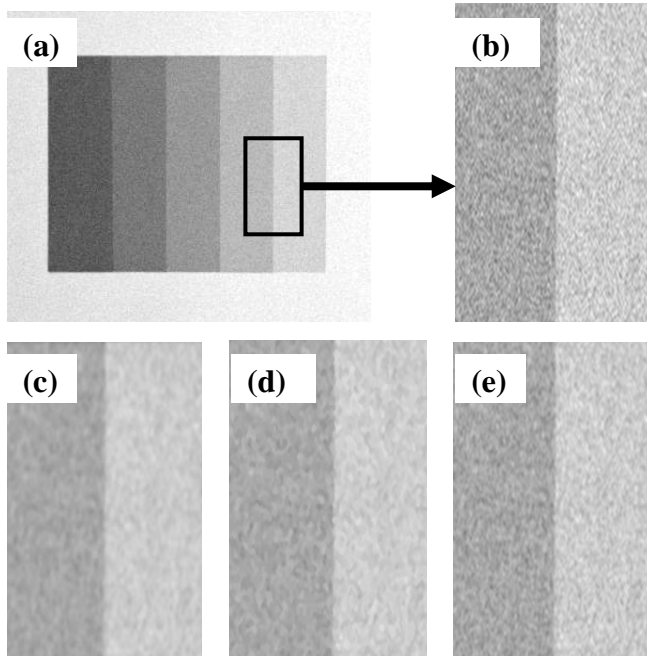


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**Table 1.** A data matrix of frequency for  $Y$  outputs to  $X$  inputs. The columns and rows of this table represent various discrete inputs and outputs. The capitals  $X$  and  $Y$  stand for the number of input and output categories, respectively. The total of all frequencies is given by  $n$ .

		Input $x$							
		$x_1$	$x_2$		$x_i$		$X$		
Output $y$	$y_1$	$n_{11}$	$n_{21}$	--	$n_{i1}$	--	--	$n_{X1}$	$n_{j=1}$
	$y_2$	$n_{12}$	$n_{22}$	--	$n_{i2}$	--	--	$n_{X2}$	$n_{j=2}$
	$y_3$	$n_{13}$	$n_{23}$	--	$n_{i3}$	--	--	$n_{X3}$	$n_{j=3}$
		--	--	--	--	--	--	--	--
	$y_j$	$n_{1j}$	$n_{2j}$	--	$n_{ij}$	--	--	$n_{Xj}$	$n_{j=j}$
		--	--	--	--	--	--	--	--
	$Y$	$n_{1Y}$	$n_{2Y}$	--	$n_{iY}$	--	--	$n_{XY}$	$n_{j=Y}$
		$n_{i=1}$	$n_{i=2}$	--	$n_{i=i}$	--	--	$n_{i=X}$	<b><math>n</math></b>



Table 3. Several typical values of transmitted information  $T(x;y)$  and conditional entropy  $H_x(y)$  obtained at the relative exposure doses of 20 and 30 for three different exposure positions. Values shown are expressed as mean $\pm$  standard deviation.

Stepwedge	Relative exposure dose	Position	$T(x;y)$ [bit]	$H_x(y)$ [bit]
A	20	center	1.72 $\pm$ 0.03	6.56 $\pm$ 0.04
		off center 15cm	1.61 $\pm$ 0.01	6.51 $\pm$ 0.01
		off center 30cm	1.57 $\pm$ 0.01	6.65 $\pm$ 0.01
	30	center	1.92 $\pm$ 0.01	6.37 $\pm$ 0.01
		off center 15cm	1.86 $\pm$ 0.01	6.24 $\pm$ 0.02
		off center 30cm	1.83 $\pm$ 0.01	6.25 $\pm$ 0.01
B	20	center	0.76 $\pm$ 0.03	6.32 $\pm$ 0.01
		off center 15cm	0.60 $\pm$ 0.03	6.26 $\pm$ 0.01
		off center 30cm	0.52 $\pm$ 0.01	6.24 $\pm$ 0.01
	30	center	0.95 $\pm$ 0.03	6.04 $\pm$ 0.01
		off center 15cm	0.77 $\pm$ 0.02	5.90 $\pm$ 0.01
		off center 30cm	0.71 $\pm$ 0.02	5.96 $\pm$ 0.01

**Table 4. Values of transmitted information  $T(x;y)$ , conditional entropy  $H_x(y)$ , noise level RMS and edge slop for three filter-processed images and original image**

Image	$T(x;y)$ [bit]	$H_x(y)$ [bit]	RMS	Edge slope
Averaging	2.55	5.75	13.2	10.6
Median	2.48	6.03	16.7	14.8
Gaussian	2.26	6.47	21.9	15
Original	1.89	6.97	31.3	17.2

The exposure conditions used to obtain the original images were:

42kV, 10mA, 0.1 sec.